

Tribhuvan University  
Institute of Science and Technology  
2076  
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Bachelor Level / First Year / Second Semester / Science  
Computer Science and Information Technology (MTH. 163)  
(Mathematics II)  
**(NEW COURSE)**

Full Marks: 80  
Pass Marks: 32  
Time: 3 hours.

Candidates are required to give their answers in their own words as far as practicable.  
The figures in the margin indicate full marks.

Group- A

3×10=30

Attempt any **THREE** questions.

1. When a system of linear equation is consistent and inconsistent? Give an example for each. Test the consistency and solve the system of equations:  $x-2y=5$ ,  $-x+y+5z=2$ ,  $y+z=0$ . [2+2+6]
2. What is the condition of a matrix to have an inverse? Find the inverse of the matrix

$$A = \begin{bmatrix} 5 & 1 & 2 \\ 1 & 0 & 3 \\ 4 & -3 & 8 \end{bmatrix}, \text{ if it exists.}$$

[2+8]

3. Find the least-square solution of  $Ax=b$  for  $A = \begin{bmatrix} 1 & -6 \\ 1 & -2 \\ 1 & 1 \\ 1 & 7 \end{bmatrix}$  and  $b = \begin{bmatrix} -1 \\ 2 \\ 1 \\ 6 \end{bmatrix}$ . [10]

4. Let  $T$  is a linear transformation. Find the standard matrix of  $T$  such that
- (i)  $T: \mathbb{R}^2 \rightarrow \mathbb{R}^4$  by  $T(e_1) = (3, 1, 3, 1)$  and  $T(e_2) = (-5, 2, 0, 0)$  where  $e_1 = (1, 0)$  and  $e_2 = (0, 1)$ ;
- (ii)  $T: \mathbb{R}^2 \rightarrow \mathbb{R}^4$  rotates point as the origin through  $\frac{3\pi}{2}$  radians counter clockwise.
- (iii)  $T: \mathbb{R}^2 \rightarrow \mathbb{R}^4$  is a vertical shear transformation that maps  $e_1$  into  $e_1 - 2e_2$  but leaves vector  $e_2$  unchanged. [4+3+3]

X<sup>T</sup> X A = X<sup>T</sup> B

Group- B

10×5=50

Attempt any **TEN** questions.

5. For what value of  $h$  will  $y$  be in span  $\{v_1, v_2, v_3\}$  if  $v_1 = \begin{bmatrix} 1 \\ -1 \\ -2 \end{bmatrix}$ ,  $v_2 = \begin{bmatrix} 5 \\ -4 \\ -7 \end{bmatrix}$ ,  $v_3 = \begin{bmatrix} -3 \\ 1 \\ 0 \end{bmatrix}$  and  $y = \begin{bmatrix} -4 \\ 3 \\ h \end{bmatrix}$ ? [5]
6. Let us define a linear transformation  $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  by  $T(x) = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} -x_2 \\ x_1 \end{bmatrix}$ . Find the image under  $T$  of  $u = \begin{bmatrix} 4 \\ 1 \end{bmatrix}$ ,  $v = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$ , and  $u+v = \begin{bmatrix} 6 \\ 4 \end{bmatrix}$ . [5]

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7. Let  $A = \begin{bmatrix} 2 & 5 \\ -3 & 1 \end{bmatrix}$  and  $B = \begin{bmatrix} 4 & -5 \\ 3 & k \end{bmatrix}$ . Determine the value (s) of  $k$  if any will make  $AB = BA$ . [5]

8. Define determinant. Compute the determinant without expanding  $\begin{vmatrix} -2 & 8 & -9 \\ -1 & 7 & 0 \\ 1 & -4 & 2 \end{vmatrix}$ . [1+4]

9. Define null space. Find the basis for the null space of the matrix  $A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 3 & 4 \end{bmatrix}$ . [1+4]

10. Let  $B = \{b_1, b_2\}$  and  $C = \{c_1, c_2\}$  be bases for a vector space  $V$ , and suppose  $b_1 = -c_1 + 4c_2$  and  $b_2 = 5c_1 - 3c_2$ . Find the change of coordinate matrix for a vector space and find  $[x]_C$  for  $x = 5b_1 + 3b_2$ . [2.5+2.5]

11. Find the eigenvalues of the matrix  $\begin{bmatrix} 6 & 5 \\ -8 & -6 \end{bmatrix}$ . [5]

12. Find the QR factorization of the matrix  $\begin{bmatrix} 2 & 1 \\ 3 & -1 \end{bmatrix}$ .  $A = QR$   
 $R = Q^T A$  [5]

13. Define binary operation. Determine whether the binary operation  $*$  is associative or commutative or both where  $*$  is defined on  $\mathbb{Q}$  by letting  $x*y = \frac{x+y}{3}$ . [5]

14. Show that the ring  $(\mathbb{Z}_4, +, \cdot)$  is an integral domain. [5]

15. Find the vector  $x$  determined by the coordinate vector  $[x]_\beta = \begin{bmatrix} -4 \\ 8 \\ -7 \end{bmatrix}$  where

$$\beta = \left\{ \begin{bmatrix} -1 \\ 2 \\ 0 \end{bmatrix}, \begin{bmatrix} 3 \\ -5 \\ 2 \end{bmatrix}, \begin{bmatrix} 4 \\ -7 \\ 3 \end{bmatrix} \right\}. \quad [5]$$